

SPIE Conference: SS04 Electro-Active Polymer Actuators and Devices
Chair: Yoseph Bar-Cohen

ABSTRACT TITLE: A CAE Approach in Application of Nafion-Pt Composite (ICPF) Actuators
--- Analysis for Surface Wipers of NASA MUSES-CN Nanorovers ---

AUTHOR LISTING:

Satoshi Tadokoro 1, Masahiro Fukuhara 1, Yoseph Bar-Cohen 2
Keisuke Oguro 3 and Toshi Takamori 1,

1 Dept. Computer & Systems Eng., Kobe University, Rokkodai, Nada, Kobe, 657-8501, Japan
Tel. +81-78-803-6229 Fax. +81-78-803-6390, Email tadokoro@octopus.cs.kobe-u.ac.jp

2 Jet Propulsion Laboratory
4800 Oak Grove Drive, Pasadena, CA 91109-8099, USA, Tel. +1-818-354-2610 Fax. +1-818-393-4057
Email yosi@jpl.nasa.gov

3 Osaka National Research Institute, Midorigaoka 1-8-31, Ikeda, Osaka 563-8577, Japan
Tel. +81-727-51-9653 Fax. +81-727-51-9629, Email oguro@onri.go.jp

PRESENTATION:

Oral Presentation

ABSTRACT TEXT:

Nafion-Pt composite (ICPF) is one of the most practical electroactive polymer nearest to applications. CAE modeling of the actuator characteristics is an essential issue for mechanical and electrical design. Kanno-Tadokoro model is a gray-box model applicable to CAE systems. It consists of 3 stages: an electrical property, a stress generation property, and a mechanical property. In the electrical property, the input is voltage and the output is distributed current through the membrane. This model consists of distributed 3 elements: resistance of porous platinum surfaces, resistance of Nafion, and RC elements approximating experimental voltage-current response. In the stress generation stage, the input is current and the output is internal stress. The relation is expressed by an equation similar to piezoelectric materials. A current vector is transformed into a stress tensor by a matrix such as the piezoelectric coefficient matrix and by a second order delay. The mechanical property is approximated by a elastic body or a viscoelastic body. This model was applied to analysis of a surface wiper to remove dust from the visual/IR window of the Nanorover of NASA MUSES-CN mission.

As a result of simulation, the following were revealed.

- Strain near the electrode was larger than that at the tip.
- Short actuator shapes sometimes had a good performance.
- Bending in the diagonal direction spoiled the objective motion.
- Crosspieces preventing diagonal bending improved the motion.
- The performance was good at resonance frequencies.

KEY WORDS:

Electroactive Polymers, ICPF, Linear Model, MUSES-CN, Wiper Design

BRIEF BIOGRAPHY:

1984: M.E. degree from the University of Tokyo,

1991: D.E. degree

1984-1993: research associate in Kobe University

1993-: associate professor in Kobe University.

Research interest: new actuators and robotics

Award: Hydraulic and Pneumatic Technology Foundation Award in 1993